

# A tour on Bridgeland stability

**Paolo Stellari**



UNIVERSITÀ  
DEGLI STUDI  
DI MILANO

Hamburg, June 2015

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting

- 1** Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2** Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2 Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3 Bridgeland stability
  - Definition and examples
  - Open problems and results

# Motivation

# Motivation

Stability conditions were introduced by [Bridgeland](#) to make the notion of  $\Pi$ -stability by Douglas rigorous.

# Motivation

Stability conditions were introduced by [Bridgeland](#) to make the notion of  $\Pi$ -stability by Douglas rigorous.

They should provide a generalization of the usual Kähler cone according to String Theory and Mirror Symmetry.

# Motivation

Stability conditions were introduced by [Bridgeland](#) to make the notion of  $\Pi$ -stability by Douglas rigorous.

They should provide a generalization of the usual Kähler cone according to String Theory and Mirror Symmetry.

*Whereof one cannot speak, thereof one must be silent.*

L. Wittgenstein, Tractatus logico-philosophicus



# Motivation

Stability conditions were introduced by [Bridgeland](#) to make the notion of  $\Pi$ -stability by Douglas rigorous.

They should provide a generalization of the usual Kähler cone according to String Theory and Mirror Symmetry.

*Whereof one cannot speak, thereof one must be silent.*

L. Wittgenstein, Tractatus logico-philosophicus

Thus we take a different perspective:

# Motivation

Stability conditions were introduced by [Bridgeland](#) to make the notion of  $\Pi$ -stability by Douglas rigorous.

They should provide a generalization of the usual Kähler cone according to String Theory and Mirror Symmetry.

*Whereof one cannot speak, thereof one must be silent.*

L. Wittgenstein, Tractatus logico-philosophicus

Thus we take a different perspective: we present Bridgeland stability conditions as emerging from the quest of a general approach to the geometry of moduli spaces.

- 1** Moduli spaces and stability
  - Curves
    - Stability
    - Recasting
- 2** Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3** Bridgeland stability
  - Definition and examples
  - Open problems and results

# The baby example

Let  $E$  be an **elliptic curve**. Namely,

# The baby example

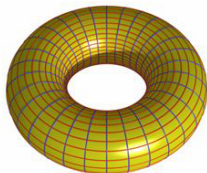
Let  $E$  be an **elliptic curve**. Namely,

- 1 **Topologically:** an orientable, compact connected topological surface of genus 1.

# The baby example

Let  $E$  be an **elliptic curve**. Namely,

- 1 **Topologically**: an orientable, compact connected topological surface of genus 1.



# The baby example

# The baby example

- 1 **Algebraically:** the zero locus in  $\mathbb{P}^2$  of a homogeneous polynomial of degree 3.



# The baby example

- 1 **Algebraically:** the zero locus in  $\mathbb{P}^2$  of a homogeneous polynomial of degree 3.

## Example

Consider the homogenous polynomial

$$p(x_0, x_1, x_2) = x_0^3 + x_1^3 + x_2^3.$$

# The baby example

- 1 Algebraically:** the zero locus in  $\mathbb{P}^2$  of a homogeneous polynomial of degree 3.

## Example

Consider the homogenous polynomial

$$p(x_0, x_1, x_2) = x_0^3 + x_1^3 + x_2^3.$$

Set

$$E = V(p(x_0, x_1, x_2)) := \{Q \in \mathbb{P}^2 : p(Q) = 0\} \hookrightarrow \mathbb{P}^2.$$

# The baby example

- 1 **Algebraically:** the zero locus in  $\mathbb{P}^2$  of a homogeneous polynomial of degree 3.

## Example

Consider the homogenous polynomial

$$p(x_0, x_1, x_2) = x_0^3 + x_1^3 + x_2^3.$$

Set

$$E = V(p(x_0, x_1, x_2)) := \{Q \in \mathbb{P}^2 : p(Q) = 0\} \hookrightarrow \mathbb{P}^2.$$

Then  $X$  is called **Fermat cubic curve**.

# Sheaves

By looking at  $E$  from the second point of view, the torus gains more structure:

# Sheaves

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold**

# Sheaves

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

# Sheaves

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

Thus we can define the following **sheaves**:

# Sheaves

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

Thus we can define the following **sheaves**:

- $\mathcal{O}_E$  such that, for any open subset  $U \subseteq E$ ,



By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

Thus we can define the following **sheaves**:

- $\mathcal{O}_E$  such that, for any open subset  $U \subseteq E$ ,

$$U \mapsto \mathcal{O}_E(U) := \{f: U \rightarrow \mathbb{C} : f \text{ is holomorphic}\};$$

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

Thus we can define the following **sheaves**:

- $\mathcal{O}_E$  such that, for any open subset  $U \subseteq E$ ,

$$U \mapsto \mathcal{O}_E(U) := \{f: U \rightarrow \mathbb{C} : f \text{ is holomorphic}\};$$

- Sheaves of  $\mathcal{O}_E$ -modules  $\mathcal{E}$ :

By looking at  $E$  from the second point of view, the torus gains more structure: it is clearly a **complex manifold** (roughly,  $E$  is locally the same as  $\mathbb{C}$ ).

Thus we can define the following **sheaves**:

- $\mathcal{O}_E$  such that, for any open subset  $U \subseteq E$ ,

$$U \mapsto \mathcal{O}_E(U) := \{f: U \rightarrow \mathbb{C} : f \text{ is holomorphic}\};$$

- Sheaves of  $\mathcal{O}_E$ -modules  $\mathcal{E}$ :

$$U \mapsto \mathcal{E}(U)$$

and  $\mathcal{E}(U)$  is a module over  $\mathcal{O}_E(U)$ ;

# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

$$\mathcal{E}|_U \cong (\mathcal{O}_E)|_U^{\oplus r}.$$

# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

$$\mathcal{E}|_U \cong (\mathcal{O}_E)|_U^{\oplus r}.$$

The integer  $r$  is called **rank** of  $\mathcal{E}$  and it is denoted by  $\mathrm{rk}(\mathcal{E})$ .

# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

$$\mathcal{E}|_U \cong (\mathcal{O}_E)|_U^{\oplus r}.$$

The integer  $r$  is called **rank** of  $\mathcal{E}$  and it is denoted by  $\text{rk}(\mathcal{E})$ .

We have another class of sheaves which play a role:

# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

$$\mathcal{E}|_U \cong (\mathcal{O}_E)|_U^{\oplus r}.$$

The integer  $r$  is called **rank** of  $\mathcal{E}$  and it is denoted by  $\text{rk}(\mathcal{E})$ .

We have another class of sheaves which play a role: **torsion sheaves!**



# Locally free sheaves

- A sheaf  $\mathcal{E}$  as above is a **locally free sheaf** if there exists a positive integer  $r$  such that

$$\mathcal{E}|_U \cong (\mathcal{O}_E)|_U^{\oplus r}.$$

The integer  $r$  is called **rank** of  $\mathcal{E}$  and it is denoted by  $\text{rk}(\mathcal{E})$ .

We have another class of sheaves which play a role: **torsion sheaves**!

Roughly, they are supported at points, with multiplicity.

# Moduli spaces

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

If yes, we would (sloppily) call such a geometric object **moduli space**.

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

If yes, we would (sloppily) call such a geometric object **moduli space**.

## Question 2

How do we study the geometry of these moduli spaces?

# Rank = 1

# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

- The Euler characteristic:

$$\chi(\mathcal{E}) = \dim_{\mathbb{C}} \mathrm{Hom}(\mathcal{O}_E, \mathcal{E}) - \dim_{\mathbb{C}} \mathrm{Ext}^1(\mathcal{O}_E, \mathcal{E}),$$



# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

- The Euler characteristic:

$\chi(\mathcal{E}) = \dim_{\mathbb{C}} \text{Hom}(\mathcal{O}_E, \mathcal{E}) - \dim_{\mathbb{C}} \text{Ext}^1(\mathcal{O}_E, \mathcal{E})$ , where  $\text{Ext}^1(\mathcal{O}_E, \mathcal{E})$  parametrizes extensions

$$0 \rightarrow \mathcal{E} \rightarrow \mathcal{F} \rightarrow \mathcal{O}_E \rightarrow 0.$$

# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

- The **Euler characteristic**:

$\chi(\mathcal{E}) = \dim_{\mathbb{C}} \text{Hom}(\mathcal{O}_E, \mathcal{E}) - \dim_{\mathbb{C}} \text{Ext}^1(\mathcal{O}_E, \mathcal{E})$ , where  $\text{Ext}^1(\mathcal{O}_E, \mathcal{E})$  parametrizes extensions

$$0 \rightarrow \mathcal{E} \rightarrow \mathcal{F} \rightarrow \mathcal{O}_E \rightarrow 0.$$

- Since  $E$  has genus 1, this number is also called **degree** and denoted  $\text{deg}(\mathcal{E})$ .

# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

- The **Euler characteristic**:

$\chi(\mathcal{E}) = \dim_{\mathbb{C}} \text{Hom}(\mathcal{O}_E, \mathcal{E}) - \dim_{\mathbb{C}} \text{Ext}^1(\mathcal{O}_E, \mathcal{E})$ , where  $\text{Ext}^1(\mathcal{O}_E, \mathcal{E})$  parametrizes extensions

$$0 \rightarrow \mathcal{E} \rightarrow \mathcal{F} \rightarrow \mathcal{O}_E \rightarrow 0.$$

- Since  $E$  has genus 1, this number is also called **degree** and denoted  $\text{deg}(\mathcal{E})$ .

## First example

$\mathcal{E}$  parametrizes vector bundles of rank 1 and degree 0 on itself.

# Rank = 1

For a locally free sheaf  $\mathcal{E}$ , we define the following invariants:

- The **Euler characteristic**:

$\chi(\mathcal{E}) = \dim_{\mathbb{C}} \text{Hom}(\mathcal{O}_E, \mathcal{E}) - \dim_{\mathbb{C}} \text{Ext}^1(\mathcal{O}_E, \mathcal{E})$ , where  $\text{Ext}^1(\mathcal{O}_E, \mathcal{E})$  parametrizes extensions

$$0 \rightarrow \mathcal{E} \rightarrow \mathcal{F} \rightarrow \mathcal{O}_E \rightarrow 0.$$

- Since  $E$  has genus 1, this number is also called **degree** and denoted  $\text{deg}(\mathcal{E})$ .

## First example

$E$  parametrizes vector bundles of rank 1 and degree 0 on itself. We say that  $E$  is self-dual.

- 1** Moduli spaces and stability
  - Curves
  - **Stability**
  - Recasting
- 2** Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3** Bridgeland stability
  - Definition and examples
  - Open problems and results

# Stability

## Idea

If the rank is greater than 1, we cannot hope to have a nice answer to our questions without making further assumptions on the sheaves.

## Idea

If the rank is greater than 1, we cannot hope to have a nice answer to our questions without making further assumptions on the sheaves.

We set

$$\mu(\mathcal{E}) := \begin{cases} \frac{\deg(\mathcal{E})}{\text{rk}(\mathcal{E})} & \text{if } \mathcal{E} \text{ is loc. free} \end{cases}$$



## Idea

If the rank is greater than 1, we cannot hope to have a nice answer to our questions without making further assumptions on the sheaves.

We set

$$\mu(\mathcal{E}) := \begin{cases} \frac{\deg(\mathcal{E})}{\text{rk}(\mathcal{E})} & \text{if } \mathcal{E} \text{ is loc. free} \\ +\infty & \text{otherwise.} \end{cases}$$

## Idea

If the rank is greater than 1, we cannot hope to have a nice answer to our questions without making further assumptions on the sheaves.

We set

$$\mu(\mathcal{E}) := \begin{cases} \frac{\deg(\mathcal{E})}{\operatorname{rk}(\mathcal{E})} & \text{if } \mathcal{E} \text{ is loc. free} \\ +\infty & \text{otherwise.} \end{cases}$$

It is called **slope**.

# Stability

## Definition

A sheaf  $\mathcal{E}$  is **(semi-)stable** if, for all proper and non-trivial subsheaves  $\mathcal{F} \hookrightarrow \mathcal{E}$  such that  $\text{rk}(\mathcal{F}) < \text{rk}(\mathcal{E})$ , we have  $\mu(\mathcal{F}) < (\leq)\mu(\mathcal{E})$ .

## Definition

A sheaf  $\mathcal{E}$  is **(semi-)stable** if, for all proper and non-trivial subsheaves  $\mathcal{F} \hookrightarrow \mathcal{E}$  such that  $\text{rk}(\mathcal{F}) < \text{rk}(\mathcal{E})$ , we have  $\mu(\mathcal{F}) < (\leq)\mu(\mathcal{E})$ .

We will refer to this notion of stability as **slope** or  **$\mu$  stability**.

## Definition

A sheaf  $\mathcal{E}$  is **(semi-)stable** if, for all proper and non-trivial subsheaves  $\mathcal{F} \hookrightarrow \mathcal{E}$  such that  $\text{rk}(\mathcal{F}) < \text{rk}(\mathcal{E})$ , we have  $\mu(\mathcal{F}) < (\leq)\mu(\mathcal{E})$ .

We will refer to this notion of stability as **slope** or  **$\mu$  stability**.

Fix two integers  $r > 0$  and  $d \in \mathbb{Z}$ .

## Definition

A sheaf  $\mathcal{E}$  is **(semi-)stable** if, for all proper and non-trivial subsheaves  $\mathcal{F} \hookrightarrow \mathcal{E}$  such that  $\text{rk}(\mathcal{F}) < \text{rk}(\mathcal{E})$ , we have  $\mu(\mathcal{F}) < (\leq)\mu(\mathcal{E})$ .

We will refer to this notion of stability as **slope** or  **$\mu$  stability**.

Fix two integers  $r > 0$  and  $d \in \mathbb{Z}$ . We denote by

$$M(r, d)$$

the moduli space of semi-stable sheaves on  $E$  with rank  $r$  and degree  $d$

## Definition

A sheaf  $\mathcal{E}$  is (semi-)stable if, for all proper and non-trivial subsheaves  $\mathcal{F} \hookrightarrow \mathcal{E}$  such that  $\text{rk}(\mathcal{F}) < \text{rk}(\mathcal{E})$ , we have  $\mu(\mathcal{F}) < (\leq)\mu(\mathcal{E})$ .

We will refer to this notion of stability as **slope** or  **$\mu$  stability**.

Fix two integers  $r > 0$  and  $d \in \mathbb{Z}$ . We denote by

$$M(r, d)$$

the moduli space of semi-stable sheaves on  $E$  with rank  $r$  and degree  $d$  (...or rather their S-equivalence classes).



# Moduli spaces

# Moduli spaces

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

# Moduli spaces

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

## Theorem (Atiyah)

Let  $r$  and  $d$  be coprime integers as above. Then

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

## Theorem (Atiyah)

Let  $r$  and  $d$  be coprime integers as above. Then

- $M(r, d) = M(r, d)^s$ ;

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

## Theorem (Atiyah)

Let  $r$  and  $d$  be coprime integers as above. Then

- $M(r, d) = M(r, d)^s$ ;
- $M(r, d)$  is isomorphic to  $E$ .

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

## Theorem (Atiyah)

Let  $r$  and  $d$  be coprime integers as above. Then

- $M(r, d) = M(r, d)^s$ ;
- $M(r, d)$  is isomorphic to  $E$ .

...the description can be completed in the non-coprime case as well!

We denote by  $M(r, d)^s$  the open subset of  $M(r, d)$  consisting of stable sheaves.

## Theorem (Atiyah)

Let  $r$  and  $d$  be coprime integers as above. Then

- $M(r, d) = M(r, d)^s$ ;
- $M(r, d)$  is isomorphic to  $E$ .

...the description can be completed in the non-coprime case as well! ...or for any curve.

# Filtrations



What can we say of a sheaf which is not semi-stable?

What can we say of a sheaf which is not semi-stable?

Harder–Narasimhan filtration

Any sheaf  $\mathcal{E}$  has a filtration

What can we say of a sheaf which is not semi-stable?

## Harder–Narasimhan filtration

Any sheaf  $\mathcal{E}$  has a filtration

$$0 = \mathcal{E}_0 \hookrightarrow \mathcal{E}_1 \hookrightarrow \dots \hookrightarrow \mathcal{E}_{n-1} \hookrightarrow \mathcal{E}_n = \mathcal{E}$$

such that

What can we say of a sheaf which is not semi-stable?

## Harder–Narasimhan filtration

Any sheaf  $\mathcal{E}$  has a filtration

$$0 = \mathcal{E}_0 \hookrightarrow \mathcal{E}_1 \hookrightarrow \dots \hookrightarrow \mathcal{E}_{n-1} \hookrightarrow \mathcal{E}_n = \mathcal{E}$$

such that

- The quotient  $\mathcal{E}_{i+1}/\mathcal{E}_i$  is semi-stable, for all  $i$ ;

What can we say of a sheaf which is not semi-stable?

## Harder–Narasimhan filtration

Any sheaf  $\mathcal{E}$  has a filtration

$$0 = \mathcal{E}_0 \hookrightarrow \mathcal{E}_1 \hookrightarrow \dots \hookrightarrow \mathcal{E}_{n-1} \hookrightarrow \mathcal{E}_n = \mathcal{E}$$

such that

- The quotient  $\mathcal{E}_{i+1}/\mathcal{E}_i$  is semi-stable, for all  $i$ ;
- $\mu(\mathcal{E}_1/\mathcal{E}_0) > \dots > \mu(\mathcal{E}_n/\mathcal{E}_{n-1})$ .

# First question... first answer

# First question... first answer

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

# First question... first answer

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

To get a positive answer to this question

- We have to impose some 'stability (or semi-stability) condition';



# First question... first answer

## Question 1

Is there another variety  $X$  (...or maybe something more refined...) that 'parametrizes' locally free sheaves of a given rank  $r$  on  $E$ ?

To get a positive answer to this question

- We have to impose some 'stability (or semi-stability) condition';
- Non semi-stable sheaves can then be filtered by semi-stable ones.

- 1** Moduli spaces and stability
  - Curves
  - Stability
  - **Recasting**
- 2** Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3** Bridgeland stability
  - Definition and examples
  - Open problems and results

# Recasting 1

# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

- (a) We take the category of all (coherent) sheaves on  $E$ :  
locally free sheaves + torsion sheaves.

# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

- (a) We take the category of all (coherent) sheaves on  $E$ :  
locally free sheaves + torsion sheaves.

We spoke about

# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

- (a) We take the category of all (coherent) sheaves on  $E$ :  
locally free sheaves + torsion sheaves.

We spoke about

- Subobjects (definition of slope stability);

# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

- (a) We take the category of all (coherent) sheaves on  $E$ :  
locally free sheaves + torsion sheaves.

We spoke about

- Subobjects (definition of slope stability);
- Quotients and extensions (HN filtrations).



# Recasting 1

An equivalent way to define the slope stability introduced in the previous slides is the following:

- (a) We take the category of all (coherent) sheaves on  $E$ :  
locally free sheaves + torsion sheaves.

We spoke about

- Subobjects (definition of slope stability);
- Quotients and extensions (HN filtrations).

We are using that the category is [abelian](#).

# Recasting 2

## Recasting 2

(b) A function  $Z$  defined, for all sheaves  $\mathcal{E}$ , as

## Recasting 2

(b) A function  $Z$  defined, for all sheaves  $\mathcal{E}$ , as

$$Z(\mathcal{E}) = -\deg(\mathcal{E}) + \sqrt{-1}\mathrm{rk}(\mathcal{E}) \in \mathbb{C}.$$

## Recasting 2

(b) A function  $Z$  defined, for all sheaves  $\mathcal{E}$ , as

$$Z(\mathcal{E}) = -\deg(\mathcal{E}) + \sqrt{-1}\mathrm{rk}(\mathcal{E}) \in \mathbb{C}.$$

Observe that:

## Recasting 2

(b) A function  $Z$  defined, for all sheaves  $\mathcal{E}$ , as

$$Z(\mathcal{E}) = -\deg(\mathcal{E}) + \sqrt{-1}\mathrm{rk}(\mathcal{E}) \in \mathbb{C}.$$

Observe that:

- $\mathrm{rk}(\mathcal{E}) \geq 0$  and if  $\mathrm{rk}(\mathcal{E}) = 0$ , then  $\deg(\mathcal{E}) > 0$ .

## Recasting 2

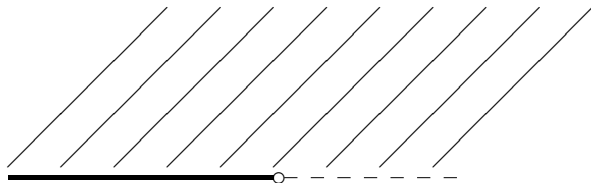
(b) A function  $Z$  defined, for all sheaves  $\mathcal{E}$ , as

$$Z(\mathcal{E}) = -\deg(\mathcal{E}) + \sqrt{-1}\mathrm{rk}(\mathcal{E}) \in \mathbb{C}.$$

Observe that:

- $\mathrm{rk}(\mathcal{E}) \geq 0$  and if  $\mathrm{rk}(\mathcal{E}) = 0$ , then  $\deg(\mathcal{E}) > 0$ . Hence, for  $\mathcal{E} \neq 0$ ,

$$Z(\mathcal{E}) \in \mathbb{R}_{>0} e^{(0,1]\sqrt{-1}\pi}.$$



# Recasting 3



# Recasting 3

- Any object in the abelian category has a filtration with respect to the function

$$-\frac{\operatorname{Re}(Z)}{\operatorname{Im}(Z)}$$

# Recasting 3

- Any object in the abelian category has a filtration with respect to the function

$$-\frac{\operatorname{Re}(Z)}{\operatorname{Im}(Z)} (= \mu)$$

# Recasting 3

- Any object in the abelian category has a filtration with respect to the function

$$-\frac{\operatorname{Re}(Z)}{\operatorname{Im}(Z)} (= \mu)$$

Such a filtration is actually unique.

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2 Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3 Bridgeland stability
  - Definition and examples
  - Open problems and results

# The problem

# The problem

Let  $X_1$  be any smooth projective variety (i.e. with an embedding in some projective space). Suppose that  $M_1$  is a moduli space of (semi-)stable sheaves on  $X_1$ .

# The problem

Let  $X_1$  be any smooth projective variety (i.e. with an embedding in some projective space). Suppose that  $M_1$  is a moduli space of (semi-)stable sheaves on  $X_1$ .

The second question we formulated before is:

# The problem

Let  $X_1$  be any smooth projective variety (i.e. with an embedding in some projective space). Suppose that  $M_1$  is a moduli space of (semi-)stable sheaves on  $X_1$ .

The second question we formulated before is:

## Question 2

How do we study the geometry of  $M_1$ ?



# First try: comparing moduli spaces

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a 'functorial association'

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a 'functorial association'

$$\Phi : \mathcal{E} \in M_1$$

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a 'functorial association'

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;
- $\Phi(\mathcal{E})$  is (semi-)stable.

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;
- $\Phi(\mathcal{E})$  is (semi-)stable.

Set  $M_2$  to be the moduli space of (semi-)stable sheaves on  $X_2$  containing  $\Phi(\mathcal{E})$ .



# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;
- $\Phi(\mathcal{E})$  is (semi-)stable.

Set  $M_2$  to be the moduli space of (semi-)stable sheaves on  $X_2$  containing  $\Phi(\mathcal{E})$ .

Hope

$\Phi$  is so natural that it induces an isomorphism  $M_1 \cong M_2$ .

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;
- $\Phi(\mathcal{E})$  is (semi-)stable.

Set  $M_2$  to be the moduli space of (semi-)stable sheaves on  $X_2$  containing  $\Phi(\mathcal{E})$ .

Hope

$\Phi$  is so natural that it induces an isomorphism  $M_1 \cong M_2$ . Just study  $M_2$ !

# First try: comparing moduli spaces

There is another complex manifold  $X_2$  and a ‘functorial association’

$$\Phi : \mathcal{E} \in M_1 \mapsto \Phi(\mathcal{E})$$

such that

- $\Phi(\mathcal{E})$  is a (coherent) sheaf on  $X_2$ ;
- $\Phi(\mathcal{E})$  is (semi-)stable.

Set  $M_2$  to be the moduli space of (semi-)stable sheaves on  $X_2$  containing  $\Phi(\mathcal{E})$ .

## Hope

$\Phi$  is so natural that it induces an isomorphism  $M_1 \cong M_2$ . Just study  $M_2$ ! ...which might be simpler if we are smart choosing  $\Phi$ .

# Derived categories

# Derived categories

To make this precise, we have to substitute the category of (coherent) sheaves on  $X_i$  with  $D^b(X_i)$ , where

# Derived categories

To make this precise, we have to substitute the category of (coherent) sheaves on  $X_i$  with  $D^b(X_i)$ , where

- The objects in  $D^b(X_i)$  are bounded complexes of coherent sheaves,

# Derived categories

To make this precise, we have to substitute the category of (coherent) sheaves on  $X_i$  with  $D^b(X_i)$ , where

- The objects in  $D^b(X_i)$  are bounded complexes of coherent sheaves, i.e.

$$\mathcal{E}^\bullet := \{0 \cdots \rightarrow \mathcal{E}^{p-1} \xrightarrow{d^{p-1}} \mathcal{E}^p \xrightarrow{d^p} \mathcal{E}^{p+1} \rightarrow \cdots \rightarrow 0\},$$

with  $d^q \circ d^{q-1} = 0$ .

# Derived categories

To make this precise, we have to substitute the category of (coherent) sheaves on  $X_i$  with  $D^b(X_i)$ , where

- The objects in  $D^b(X_i)$  are bounded complexes of coherent sheaves, i.e.

$$\mathcal{E}^\bullet := \{0 \cdots \rightarrow \mathcal{E}^{p-1} \xrightarrow{d^{p-1}} \mathcal{E}^p \xrightarrow{d^p} \mathcal{E}^{p+1} \rightarrow \cdots \rightarrow 0\},$$

with  $d^q \circ d^{q-1} = 0$ .

- The morphisms are slightly complicated: they are a localization of the usual morphisms of complexes.



# Derived categories

To make this precise, we have to substitute the category of (coherent) sheaves on  $X_i$  with  $D^b(X_i)$ , where

- The objects in  $D^b(X_i)$  are bounded complexes of coherent sheaves, i.e.

$$\mathcal{E}^\bullet := \{0 \cdots \rightarrow \mathcal{E}^{p-1} \xrightarrow{d^{p-1}} \mathcal{E}^p \xrightarrow{d^p} \mathcal{E}^{p+1} \rightarrow \cdots \rightarrow 0\},$$

with  $d^q \circ d^{q-1} = 0$ .

- The morphisms are slightly complicated: they are a localization of the usual morphisms of complexes. But we do not need to understand them properly here...

# Fourier–Mukai functors 1

# Fourier–Mukai functors 1

We are now in good shape to make the previous construction rigorous:

# Fourier–Mukai functors 1

We are now in good shape to make the previous construction rigorous:

- Take  $X_1$  and  $X_2$  be smooth projective varieties. Let  $p_i : X_1 \times X_2 \rightarrow X_i$  be the natural projection. Take  $\mathcal{F} \in D^b(X_1 \times X_2)$ .

# Fourier–Mukai functors 1

We are now in good shape to make the previous construction rigorous:

- Take  $X_1$  and  $X_2$  be smooth projective varieties. Let  $p_i : X_1 \times X_2 \rightarrow X_i$  be the natural projection. Take  $\mathcal{F} \in D^b(X_1 \times X_2)$ .
- For  $\mathcal{E} \in D^b(X_1)$ , we set

# Fourier–Mukai functors 1

We are now in good shape to make the previous construction rigorous:

- Take  $X_1$  and  $X_2$  be smooth projective varieties. Let  $p_i : X_1 \times X_2 \rightarrow X_i$  be the natural projection. Take  $\mathcal{F} \in D^b(X_1 \times X_2)$ .
- For  $\mathcal{E} \in D^b(X_1)$ , we set

$$\Phi_{\mathcal{F}}(\mathcal{E}) := (p_2)_*(\mathcal{F} \otimes p_1^*(\mathcal{E}))$$

# Fourier–Mukai functors 1

We are now in good shape to make the previous construction rigorous:

- Take  $X_1$  and  $X_2$  be smooth projective varieties. Let  $p_i : X_1 \times X_2 \rightarrow X_i$  be the natural projection. Take  $\mathcal{F} \in D^b(X_1 \times X_2)$ .
- For  $\mathcal{E} \in D^b(X_1)$ , we set

$$\Phi_{\mathcal{F}}(\mathcal{E}) := (p_2)_*(\mathcal{F} \otimes p_1^*(\mathcal{E}))$$

## Definition

A functor isomorphic to one as above is called **Fourier–Mukai functor**. And  $\mathcal{F}$  is its **Fourier–Mukai kernel**.

# Fourier–Mukai functors 2



# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

$$(p_2)_*$$

# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

$$(p_2)_* \implies \int$$

# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

$$(p_2)_* \mathcal{F} \otimes \mathcal{O}(\mathbb{P}^1) \implies \int$$

# Fourier–Mukai functors 2

- 1** **Fourier:** these are sheafifications of the usual Fourier transform

$$\begin{array}{ll} (p_2)_* & \implies \int \\ \mathcal{F} \otimes & \implies \text{multiplication by the Fourier kernel.} \end{array}$$

# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

$$\begin{aligned} (p_2)_* &\implies \int \\ \mathcal{F} \otimes &\implies \text{multiplication by the Fourier kernel.} \end{aligned}$$

- 2 **Mukai:** Used by Mukai to study moduli spaces on abelian varieties (i.e. higher dimensional analogues of elliptic curves).

# Fourier–Mukai functors 2

- 1 **Fourier:** these are sheafifications of the usual Fourier transform

$$\begin{aligned} (p_2)_* &\implies \int \\ \mathcal{F} \otimes &\implies \text{multiplication by the Fourier kernel.} \end{aligned}$$

- 2 **Mukai:** Used by Mukai to study moduli spaces on abelian varieties (i.e. higher dimensional analogues of elliptic curves).
- 3 **Hodge:** ‘Categorification’ of the usual notion of correspondence.

# Disadvantages



# Disadvantages

These functors are (essentially) always a natural choice and they make our first try work in several interesting examples.

# Disadvantages

These functors are (essentially) always a natural choice and they make our first try work in several interesting examples.

But, in general,

# Disadvantages

These functors are (essentially) always a natural choice and they make our first try work in several interesting examples.

But, in general,

- 1 FM functors do not send sheaves to sheaves.

# Disadvantages

These functors are (essentially) always a natural choice and they make our first try work in several interesting examples.

But, in general,

- 1 FM functors do not send sheaves to sheaves.
- 2 FM functors do not preserve stability, in the sense we explained before.

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2 Geometry out of stability**
  - Fourier–Mukai transforms
  - Varying stability**
- 3 Bridgeland stability
  - Definition and examples
  - Open problems and results

# Second try: varying stability 1

## Second try: varying stability 1

Suppose that  $X$  carries many different types of stability ([stability conditions](#)) and that all these stability conditions are nicely parametrized by a geometric object  $S$ .

## Second try: varying stability 1

Suppose that  $X$  carries many different types of stability ([stability conditions](#)) and that all these stability conditions are nicely parametrized by a geometric object  $S$ .

Then one may start with a moduli space  $M$  of  $\mu$ -stable sheaves and begin changing stability inside  $S$ .



## Second try: varying stability 2

## Second try: varying stability 2

- There might be regions (**chambers**) of  $S$  where  $M$  does not change even if stability is changing.

## Second try: varying stability 2

- There might be regions (**chambers**) of  $S$  where  $M$  does not change even if stability is changing.
- But passing through a different region (**wall**) of  $S$ , all sheaves in  $M$  get destabilized and  $M$  has to be replaced by a different moduli space  $M'$  of stable sheaves.

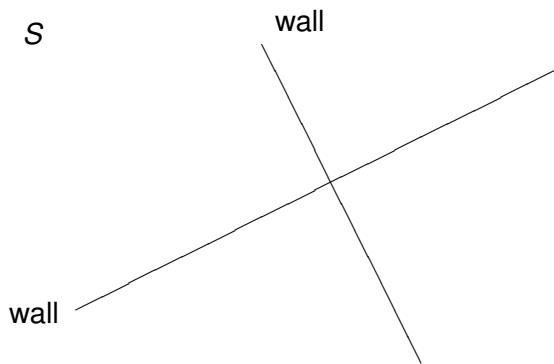
## Second try: varying stability 2

- There might be regions (**chambers**) of  $S$  where  $M$  does not change even if stability is changing.
- But passing through a different region (**wall**) of  $S$ , all sheaves in  $M$  get destabilized and  $M$  has to be replaced by a different moduli space  $M'$  of stable sheaves.

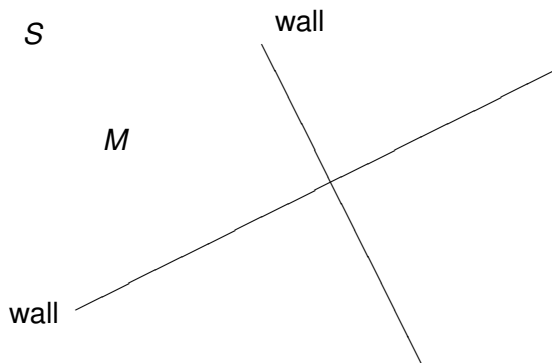
We call this **wall-crossing phenomenon**.

## Second try: varying stability 3

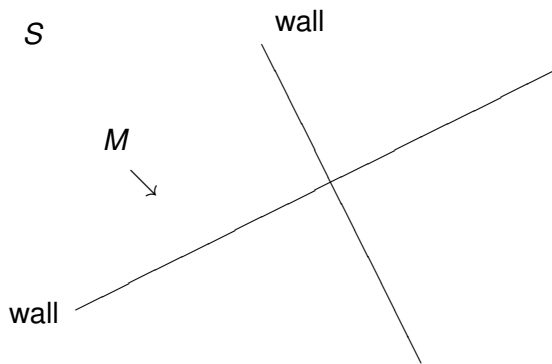
## Second try: varying stability 3



## Second try: varying stability 3

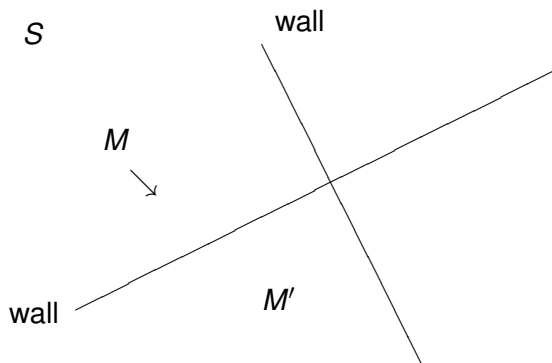


## Second try: varying stability 3

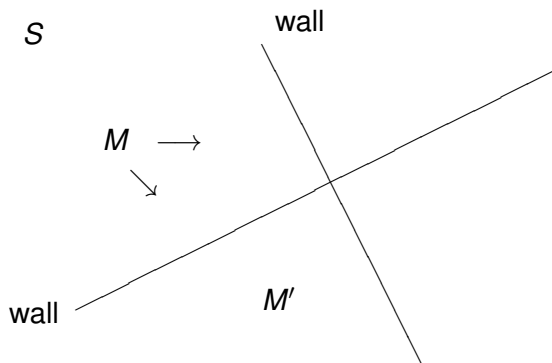




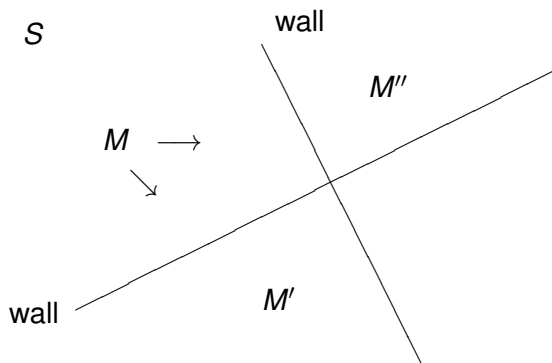
## Second try: varying stability 3



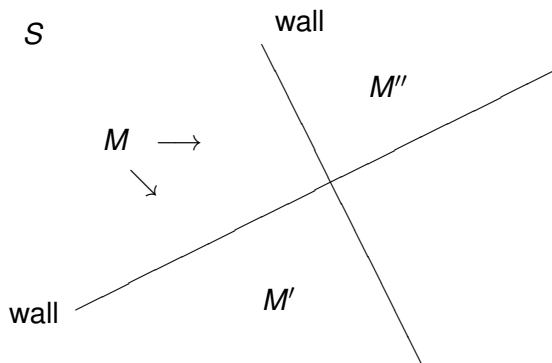
## Second try: varying stability 3



## Second try: varying stability 3



## Second try: varying stability 3



During this process, we might get  $M'$  and  $M''$  **birational** to  $M$ : this means that  $M$  and  $M'$  (or  $M''$ ) are isomorphic just along open subsets.

## Second try: varying stability 4

## Second try: varying stability 4

To make this more precise, one should consider (twisted) Gieseker stability.

## Second try: varying stability 4

To make this more precise, one should consider (twisted) Gieseker stability.

Variation of this stability means then variation of the corresponding polarization.

## Second try: varying stability 4

To make this more precise, one should consider (twisted) Gieseker stability.

Variation of this stability means then variation of the corresponding polarization.

This, in turn, is related to variations of GIT quotients:



## Second try: varying stability 4

To make this more precise, one should consider (twisted) Gieseker stability.

Variation of this stability means then variation of the corresponding polarization.

This, in turn, is related to variations of GIT quotients: Thaddeus, Matsuki–Wentworth, ...

# Hope and bad news

# Hope and bad news

## Question 2'

By varying stability, can we get all birational models of  $M$ ?

# Hope and bad news

## Question 2'

By varying stability, can we get all birational models of  $M$ ?

Again, variations of the usual stability cannot be sufficient to get such a complete picture.

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2 Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3 Bridgeland stability
  - Definition and examples
  - Open problems and results

# Main idea

# Main idea

The two methods we described:

The two methods we described:

- 1 Apply FM functors and change the model;



The two methods we described:

- 1 Apply FM functors and change the model;
- 2 Vary stability and look for all birational models

The two methods we described:

- 1 Apply FM functors and change the model;
- 2 Vary stability and look for all birational models

are very simple and promising

# Main idea

The two methods we described:

- 1 Apply FM functors and change the model;
- 2 Vary stability and look for all birational models

are very simple and promising ...but they do not fit nicely with the usual notion of stability...

# Main idea

The two methods we described:

- 1 Apply FM functors and change the model;
- 2 Vary stability and look for all birational models

are very simple and promising ...but they do not fit nicely with the usual notion of stability...

Hence...

# Main idea

The two methods we described:

- 1 Apply FM functors and change the model;
- 2 Vary stability and look for all birational models

are very simple and promising ...but they do not fit nicely with the usual notion of stability...

Hence...

Change perspective on stability!

# Bridgeland definition (very roughly)

# Bridgeland definition (very roughly)

Simply: axiomatize and make general the recasting of  $\mu$ -stability discussed before!

# Bridgeland definition (very roughly)

Simply: axiomatize and make general the recasting of  $\mu$ -stability discussed before!

A (Bridgeland) stability condition on  $D^b(X)$ , for  $X$  a smooth projective variety, is a pair

$$\sigma = (\mathbf{A}, Z)$$

where



# Bridgeland definition (very roughly)

Simply: axiomatize and make general the recasting of  $\mu$ -stability discussed before!

A (Bridgeland) stability condition on  $D^b(X)$ , for  $X$  a smooth projective variety, is a pair

$$\sigma = (\mathbf{A}, Z)$$

where

- 1**  $\mathbf{A}$  is an abelian category (...with some technical assumptions...);

# Bridgeland definition (very roughly)

# Bridgeland definition (very roughly)

2  $Z$  is a group homomorphism such that

# Bridgeland definition (very roughly)

2  $Z$  is a group homomorphism such that

- $Z(\mathcal{E}) \in \mathbb{R}_{>0} e^{(0,1]\sqrt{-1}\pi}$ , for  $0 \neq \mathcal{E} \in \mathbf{A}$ ;

# Bridgeland definition (very roughly)

2  $Z$  is a group homomorphism such that

- $Z(\mathcal{E}) \in \mathbb{R}_{>0} e^{(0,1]\sqrt{-1}\pi}$ , for  $0 \neq \mathcal{E} \in \mathbf{A}$ ;
- Any  $0 \neq \mathcal{E} \in \mathbf{A}$  has a Harder–Narasimhan filtration with respect to the slope

$$-\frac{\operatorname{Re}(Z)}{\operatorname{Im}(Z)}$$

# Bridgeland definition (very roughly)

2  $Z$  is a group homomorphism such that

- $Z(\mathcal{E}) \in \mathbb{R}_{>0} e^{(0,1]\sqrt{-1}\pi}$ , for  $0 \neq \mathcal{E} \in \mathbf{A}$ ;
- Any  $0 \neq \mathcal{E} \in \mathbf{A}$  has a Harder–Narasimhan filtration with respect to the slope

$$-\frac{\operatorname{Re}(Z)}{\operatorname{Im}(Z)}$$

3 **Kontsevich–Soibelman**: support property (ensuring that, if we have one stability condition, then we get an entire open subset).

# Properties (Bridgeland)

# Properties (Bridgeland)

- Bridgeland stability is preserved under Fourier–Mukai equivalences;



# Properties (Bridgeland)

- Bridgeland stability is preserved under Fourier–Mukai equivalences;
- The space  $\text{Stab}(\mathcal{D}^b(X))$ , parametrizing Bridgeland stability conditions, is actually a complex manifold of finite dimension. Moreover  $\text{Stab}(\mathcal{D}^b(X))$  has a wall and chamber structure.

# Properties (Bridgeland)

- Bridgeland stability is preserved under Fourier–Mukai equivalences;
- The space  $\text{Stab}(\mathcal{D}^b(X))$ , parametrizing Bridgeland stability conditions, is actually a complex manifold of finite dimension. Moreover  $\text{Stab}(\mathcal{D}^b(X))$  has a wall and chamber structure.

Hence, in this setup, we can apply our two methods.

# Wall crossing 1

# Wall crossing 1

## Warning

The usual  $\mu$ -stability is a stability condition in the sense of Bridgeland if and only if the dimension of  $X$  is 1.

# Wall crossing 1

## Warning

The usual  $\mu$ -stability is a stability condition in the sense of Bridgeland if and only if the dimension of  $X$  is 1.

Thus, in general, given a moduli space  $M$  of stable sheaves on  $X$ , we first need to find a Bridgeland stability condition

$$\sigma \in \text{Stab}(\mathcal{D}^b(X))$$

# Wall crossing 1

## Warning

The usual  $\mu$ -stability is a stability condition in the sense of Bridgeland if and only if the dimension of  $X$  is 1.

Thus, in general, given a moduli space  $M$  of stable sheaves on  $X$ , we first need to find a Bridgeland stability condition

$$\sigma \in \text{Stab}(\mathcal{D}^b(X))$$

such that

$$M \cong \tilde{M},$$

# Wall crossing 1

## Warning

The usual  $\mu$ -stability is a stability condition in the sense of Bridgeland if and only if the dimension of  $X$  is 1.

Thus, in general, given a moduli space  $M$  of stable sheaves on  $X$ , we first need to find a Bridgeland stability condition

$$\sigma \in \text{Stab}(\mathcal{D}^b(X))$$

such that

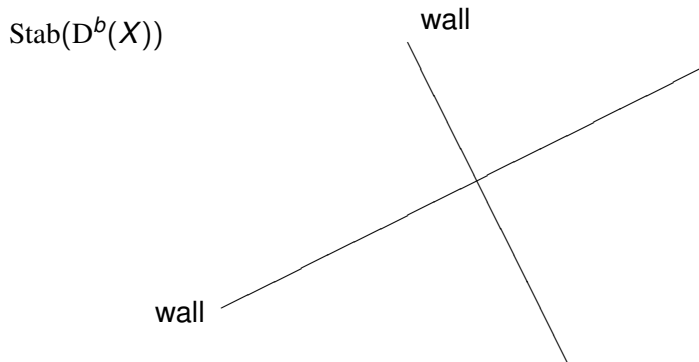
$$M \cong \tilde{M},$$

where  $\tilde{M}$  is a moduli space of  $\sigma$ -stable objects.

# Wall crossing 2



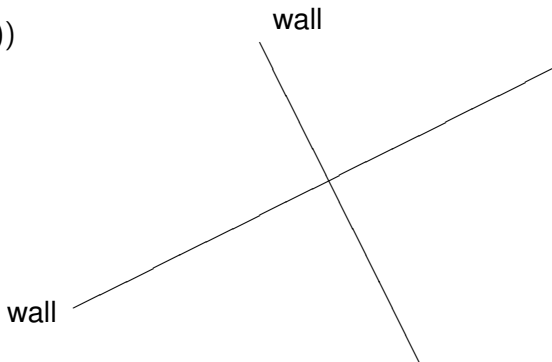
# Wall crossing 2



# Wall crossing 2

$\text{Stab}(D^b(X))$

$\infty$

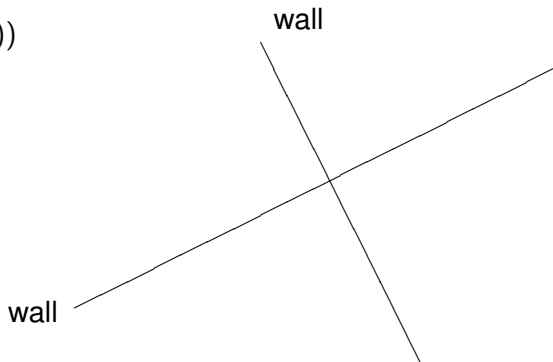


# Wall crossing 2

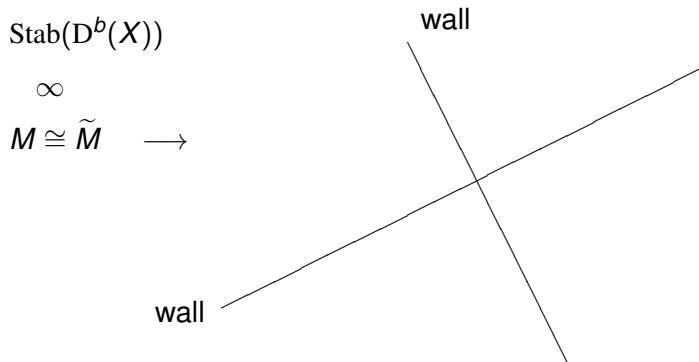
$\text{Stab}(\mathcal{D}^b(X))$

$\infty$

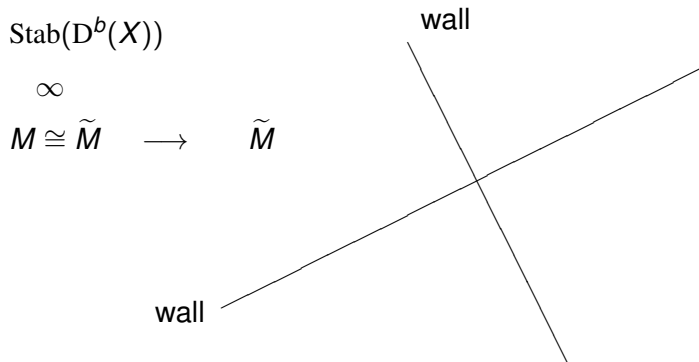
$M \cong \tilde{M}$



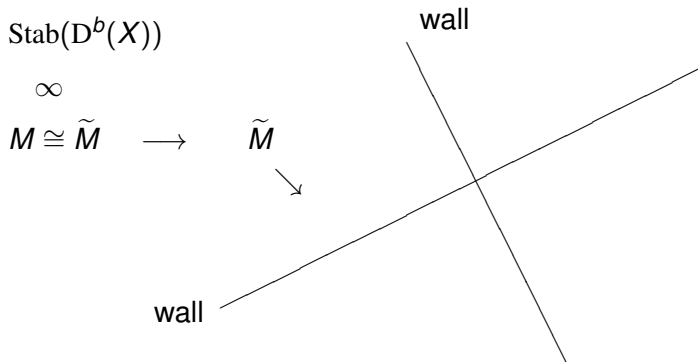
# Wall crossing 2



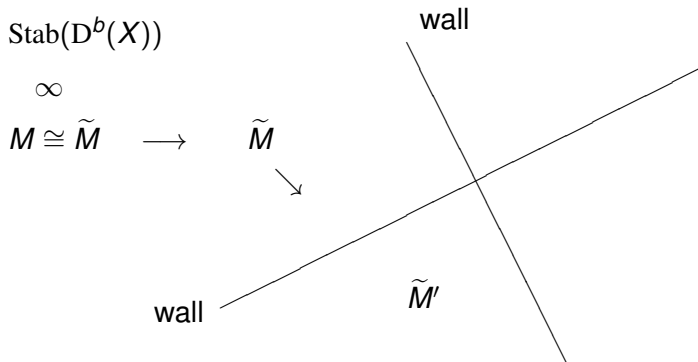
# Wall crossing 2



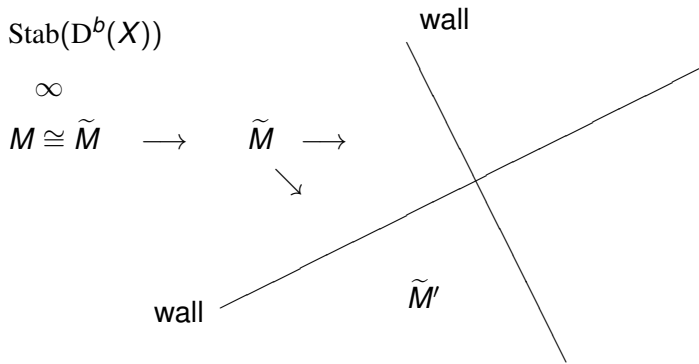
# Wall crossing 2



# Wall crossing 2

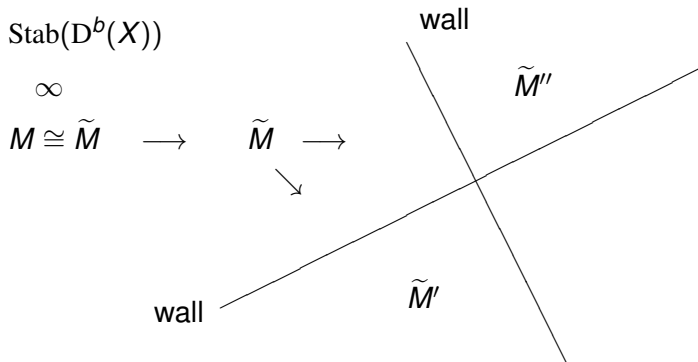


# Wall crossing 2





# Wall crossing 2



# Wall crossing 3

## Wall crossing 3

These techniques have been successfully exploited for moduli spaces of (Gieseker) stable sheaves on smooth projective complex surfaces.

## Wall crossing 3

These techniques have been successfully exploited for moduli spaces of (Gieseker) stable sheaves on smooth projective complex surfaces.

In particular, just to mention some:

## Wall crossing 3

These techniques have been successfully exploited for moduli spaces of (Gieseker) stable sheaves on smooth projective complex surfaces.

In particular, just to mention some:

- [Arcara–Bertram–Coskun–Huizenga](#): Hilbert scheme of points on the projective plane (i.e. stable sheaves with very special topological invariants);

# Wall crossing 4

- Bayer–Macrì: Moduli spaces of (Gieseker) stable sheaves on K3 surfaces (e.g. zero locus in  $\mathbb{P}^3$  of  $x_0^4 + x_1^4 + x_2^4 + x_3^4$ );

## Wall crossing 4

- **Bayer–Macrì:** Moduli spaces of (Gieseker) stable sheaves on K3 surfaces (e.g. zero locus in  $\mathbb{P}^3$  of  $x_0^4 + x_1^4 + x_2^4 + x_3^4$ );
- **Minamide–Yanagida–Yoshioka:** Moduli spaces of (Gieseker) stable sheaves on abelian surfaces.



## Wall crossing 4

- **Bayer–Macrì:** Moduli spaces of (Gieseker) stable sheaves on K3 surfaces (e.g. zero locus in  $\mathbb{P}^3$  of  $x_0^4 + x_1^4 + x_2^4 + x_3^4$ );
- **Minamide–Yanagida–Yoshioka:** Moduli spaces of (Gieseker) stable sheaves on abelian surfaces.
- **Nuer:** Moduli spaces of (Gieseker) stable sheaves on Enriques surfaces (i.e. quotients of special K3 surfaces under the action of a free involution).

- 1 Moduli spaces and stability
  - Curves
  - Stability
  - Recasting
- 2 Geometry out of stability
  - Fourier–Mukai transforms
  - Varying stability
- 3 Bridgeland stability**
  - Definition and examples
  - Open problems and results**

# Open problems 1

# Open problems 1

## Main problem

Is  $\text{Stab}(D^b(X))$  non empty, for a smooth projective variety  $X$ ?

# Open problems 1

## Main problem

Is  $\text{Stab}(D^b(X))$  non empty, for a smooth projective variety  $X$ ?

- $\dim(X) = 1$  (Bridgeland):  $\text{Stab}(D^b(X)) \neq \emptyset$ . Namely,  $\mu$ -stability is THE example.

# Open problems 1

## Main problem

Is  $\text{Stab}(D^b(X))$  non empty, for a smooth projective variety  $X$ ?

- $\dim(X) = 1$  (Bridgeland):  $\text{Stab}(D^b(X)) \neq \emptyset$ . Namely,  $\mu$ -stability is THE example.
- $\dim(X) = 2$  (Bridgeland and others): one can describe connected components of  $\text{Stab}(D^b(X)) \neq \emptyset$ .

# Open problems 1

# Open problems 1

The really challenging case is the one of smooth projective varieties of dimension 3.



# Open problems 1

The really challenging case is the one of smooth projective varieties of dimension 3.

Even more precisely, we really need to know if  $\text{Stab}(D^b(X)) \neq \emptyset$ , for a smooth projective Calabi–Yau 3-fold  $X$  or a variety with trivial canonical bundle:

# Open problems 1

The really challenging case is the one of smooth projective varieties of dimension 3.

Even more precisely, we really need to know if  $\text{Stab}(D^b(X)) \neq \emptyset$ , for a smooth projective Calabi–Yau 3-fold  $X$  or a variety with trivial canonical bundle:

- Applications to string theory and mathematical physics;

# Open problems 1

The really challenging case is the one of smooth projective varieties of dimension 3.

Even more precisely, we really need to know if  $\text{Stab}(D^b(X)) \neq \emptyset$ , for a smooth projective Calabi–Yau 3-fold  $X$  or a variety with trivial canonical bundle:

- Applications to string theory and mathematical physics;
- Counting invariants.

# Results

## Theorem (Bayer–Macrì–S.)

If  $X$  is any abelian 3-fold or some Calabi–Yau 3-folds (of quotient type), then  $\text{Stab}(D^b(X)) \neq \emptyset$ .

## Theorem (Bayer–Macrì–S.)

If  $X$  is any abelian 3-fold or some Calabi–Yau 3-folds (of quotient type), then  $\text{Stab}(D^b(X)) \neq \emptyset$ .

We prove much more: we describe a connected component as in the surface case!

## Theorem (Bayer–Macrì–S.)

If  $X$  is any abelian 3-fold or some Calabi–Yau 3-folds (of quotient type), then  $\text{Stab}(D^b(X)) \neq \emptyset$ .

We prove much more: we describe a connected component as in the surface case!

An example of [Calabi–Yau 3-folds](#) (not covered by our result) is the Fermat quintic, i.e. zero locus in  $\mathbb{P}^4$  of the homogeneous polynomial

$$x_0^5 + x_1^5 + x_2^5 + x_3^5 + x_4^5.$$

# Results



# Results

The special Calabi–Yau's we study are obtained by one of the following two constructions

# Results

The special Calabi–Yau's we study are obtained by one of the following two constructions

- Quotients of an abelian 3-fold  $A$  by the free action of a finite group  $G$  (Type A Calabi-Yau's);

# Results

The special Calabi–Yau's we study are obtained by one of the following two constructions

- Quotients of an abelian 3-fold  $A$  by the free action of a finite group  $G$  (Type A Calabi-Yau's);
- Quotients of an abelian 3-fold  $A$  by the action of a finite group  $G$  such that the quotient  $A/G$  has a crepant resolution of Calabi–Yau type.

# Results

The special Calabi–Yau's we study are obtained by one of the following two constructions

- Quotients of an abelian 3-fold  $A$  by the free action of a finite group  $G$  (Type A Calabi-Yau's);
- Quotients of an abelian 3-fold  $A$  by the action of a finite group  $G$  such that the quotient  $A/G$  has a crepant resolution of Calabi–Yau type.

## Example

For an example of the last set of CY's, one can take the product  $E \times E \times E$ , where  $E$  is an elliptic curve, and quotient by the diagonal action of  $\mathbb{Z}/3\mathbb{Z}$ .

# Results

# Results

Thus the result for Calabi–Yau 3-folds is deduced by the one for abelian 3-folds by **inducing** stability conditions.

# Results

Thus the result for Calabi–Yau 3-folds is deduced by the one for abelian 3-folds by **inducing** stability conditions.

Let  $A$  be an abelian 3-fold and let  $G$  be a finite group acting on  $A$ . Let  $\text{Stab}(D^b(A))^G$  denote  $G$ -invariant stability conditions.

# Results

Thus the result for Calabi–Yau 3-folds is deduced by the one for abelian 3-folds by **inducing** stability conditions.

Let  $A$  be an abelian 3-fold and let  $G$  be a finite group acting on  $A$ . Let  $\text{Stab}(D^b(A))^G$  denote  $G$ -invariant stability conditions.

## Macri–Mehrotra–S.

There is a closed embedding

$$\text{Stab}(D^b(A))^G \hookrightarrow \text{Stab}(D^b(Y)),$$

where  $Y$  is a crepant resolution of  $A/G$ .



# Open problems 2

## Open problems 2

The Main Problem is still open in its complete generality but the techniques developed to treat the case of abelian 3-folds seem promising, for several other 3-folds.

## Open problems 2

The Main Problem is still open in its complete generality but the techniques developed to treat the case of abelian 3-folds seem promising, for several other 3-folds.

Indeed, the non-emptiness result is known in other cases:

## Open problems 2

The Main Problem is still open in its complete generality but the techniques developed to treat the case of abelian 3-folds seem promising, for several other 3-folds.

Indeed, the non-emptiness result is known in other cases:

- **3-dimensional projective space**: Macrì, Bayer–Macrì–Toda;

## Open problems 2

The Main Problem is still open in its complete generality but the techniques developed to treat the case of abelian 3-folds seem promising, for several other 3-folds.

Indeed, the non-emptiness result is known in other cases:

- **3-dimensional projective space**: Macrì, Bayer–Macrì–Toda;
- **3-dimensional quadrics**: Schmidt;

## Open problems 2

The Main Problem is still open in its complete generality but the techniques developed to treat the case of abelian 3-folds seem promising, for several other 3-folds.

Indeed, the non-emptiness result is known in other cases:

- **3-dimensional projective space**: Macrì, Bayer–Macrì–Toda;
- **3-dimensional quadrics**: Schmidt;
- **Generic ppav**: Maciocia–Piyaratne (special case of our result).

# Open problems 3

## Problem 2

Study the birational geometry of moduli spaces of stable sheaves on 3-folds.

# Open problems 3

## Problem 2

Study the birational geometry of moduli spaces of stable sheaves on 3-folds.

This is certainly a difficult problem.



## Problem 2

Study the birational geometry of moduli spaces of stable sheaves on 3-folds.

This is certainly a difficult problem. But it could work in several interesting cases:

## Problem 2

Study the birational geometry of moduli spaces of stable sheaves on 3-folds.

This is certainly a difficult problem. But it could work in several interesting cases: special Hilbert schemes on  $\mathbb{P}^3$ .